

On the Use of the Gompertz Model to Predict Microbial Thermal Inactivation Under Isothermal and Non-Isothermal Conditions

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Abstract Food processes should be designed to provide an adequate margin of safety against microbiological risk of food poisoning and food spoilage throughout shelf life. In this field, the use of mathematical models that describe the microorganisms' kinetics in such conditions is an important tool for convenient design, control and optimization of efficient processes. If those models are accurate and precise, one can extract the best aiming at predictive purposes. The Gompertz equation is commonly applied to describe sigmoidal kinetics. Besides the proven adequacy of the model in those kinetics descriptions, most of the reported works do not use Gompertz equation in the most convenient form, and insightful information could be obtained with re-parameterized forms. This work aims at reviewing the use of the Gompertz model to describe inactivation, as well as re-parameterized forms that include parameters related to the survival curve features. Microbial survival often presents a shoulder prior to inactivation, followed by a linear phase (corresponding to a maximum inactivation rate) and a tail residual population. The versatility of the Gompertz model in describing kinetics with different shapes, varying from a log-linear tendency till a complete sigmoidal shape, makes it attractive for predictive purposes, both under static and dynamic temperature

conditions. Drawbacks and critical features of the model, when it is applied to microbial responses, will be overview.

Keywords Gompertz model · Inactivation kinetics · Isothermal and non-isothermal conditions

List of Symbols

a	Gompertz model parameter (Eq. 1)
A	Maximum microbial cell density (Eq. 2) or Gibson modified Gompertz model parameter (Eq. 3)
b	Gompertz model parameter (Eq. 1)
B	Gibson modified Gompertz model parameter (Eq. 4)
c	Gompertz model parameter (Eq. 1)
C	Gibson modified Gompertz model parameter (Eq. 3)
D	Model parameter
e	Euler's number (2.71828)
k	Inactivation rate (min^{-1})
L	Lag time or shoulder (min)
M	Gibson modified Gompertz model parameter (Eq. 3)
N	Microbial cell density (CFU ml^{-1})
R_{adj}^2	Coefficient of determination adjusted
t	Time (s or min)
y	Dependent variable

Greek

μ Specific microbial growth rate (s^{-1} or min^{-1})

Subscripts

dynamic	Relative to non-isothermal conditions
i	At the function inflexion point
inact	Relative to inactivation
max	Maximum value
orig	Relative to original Gompertz model
0	Initial value
res	Residual value

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Abbreviations

SHW_{95%} Standardized half width at 95% (%)

Introduction

Food microbiologists are giving increased attention to microbial kinetics modelling. The use of mathematical models that properly describe microbial behaviour under specific environmental conditions is important for predictive purposes and process design.

Whereas growth kinetic models are helpful for estimation of the time required for pathogens to reach dangerous levels under specific conditions, inactivation kinetic models allow prediction of pathogens survival under stressing environmental factors (such as high temperatures, low pH and reduced water activity values). Inactivation models may contribute to determine the extent to which existing thermal food processes could be modified in order to improve shelf life and quality, while maintaining safe standards.

First-order kinetic models have been extensively used to describe a log-linear microbial variation with time. However, growth/survival curves of most microbial cells do not show such tendency [42], and a sigmoidal behaviour is often observed. These curves can be characterized by three main features: (1) a lag time (or shoulder) prior to a (2) maximum growth/inactivation rate period and a (3) tail (or residual population).

Valuable reviews on microbial kinetics modelling were done by Ross and McMeekin [35], Schaffner and Labuza [36], McDonald and Sun [26], Xiong et al. [47], Xiong et al. [48] and Geeraerd et al. [14]. Concerning the dependence of the kinetic parameters with adverse factors, the works of Whiting and Buchanan [45] and Swinnen et al. [39] are supportive references. Zwietering et al. [49] and Buchanan et al. [7] compared the most relevant models used to describe microbial growth. Regarding thermal inactivation behaviour, Xiong et al. [48] gathered the most frequently used mathematical expressions. Those models describe linear and nonlinear curves, with shoulder and/or tailing phases [10, 21, 22, 32, 34]. The Gompertz and logistic functions and the Baranyi model are the most widely used expressions to describe sigmoidal microbial kinetics [2, 29].

There is a never-ending discussion about the best models (mechanistics, empiricals and stochastic) applied in this field. However, one should bear in mind that an adequate model can be considered the one that predicts the response accurately, if this is the objective, and several models may attain such target.

Mathematical models for microbial inactivation prediction are usually developed on the basis of un-realistic isothermal conditions [34], and thermal inactivation studies

related to real food processes, considering actual time-varying temperature conditions, are scarce [6, 12, 24, 37]. Parameters estimated under isothermal conditions differ from the ones obtained if non-isothermal conditions are applied [20, 41], and hazardous predictions maybe attained if parameters estimated isothermally were used to predict bacterial survival under time-varying temperature conditions.

The Gompertz Model

Gibson et al. [15], Zwietering et al. [49], Garthright [13] and Chhabra et al. [9] referred the versatility of the Gompertz model in describing log-linear kinetics as well as those containing shoulder and/or tailing effects.

The Gompertz equation [18], which is a three-parameter model, was firstly developed to express the law of human mortality. Gibson et al. [15] were pioneers in using this mathematical expression to describe asymmetrical sigmoid shape of microbial growth:

$$y_{\text{orig}}(t) = a \exp(-\exp(b - ct)) \quad (1)$$

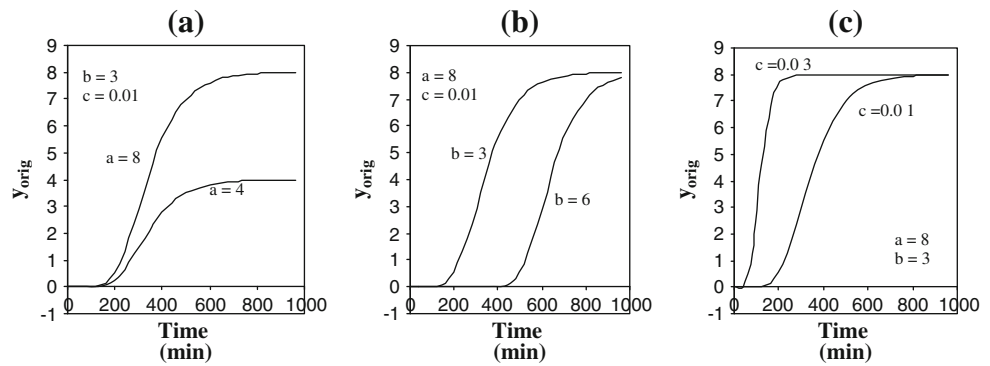
Herein, y_{orig} represents the observed response at time t , and a , b and c are model parameters (assumed to be positive). In Fig. 1, it can be observed the influence of these parameters on the function shape. With exception of the parameter a that expresses the upper limit of the function, the remaining two parameters do not give direct information on a unique curve feature.

Equation 1, and its modified forms, has been successfully applied to describe isothermal microbial growth [1, 16, 23, 28, 38] and isothermal microbial inactivation [5, 8, 19, 24, 25, 47]. McDonald and Sun [26] concluded that the Gompertz expression was the best model to describe growth tendencies, both in terms of statistical accuracy and form simplicity, when compared to other sigmoidal functions. Gibson et al. [15] arrived to similar conclusions.

Besides the extensive use of the Gompertz model, it is not clear the methodology to attain a re-parameterization of the function aiming at obtaining parameters that express a feature of the growth/survival curves. Only a small number of works linked model parameters to a microbiological occurrence, i.e. growth/survival rate and lag time/shoulder [13, 49], thus confining the advantages of using mathematical expressions in phenomena description.

Zwietering et al. [49] re-parameterized the original Gompertz equation to describe isothermal microbial growth, considering the maximum specific growth rate (μ_{max}), the lag time (L) and the maximum reached value (A) as model kinetic parameters:

Fig. 1 Influence of the original Gompertz parameters on the function shape: **a** parameter *a*, **b** parameter *b* and **c** parameter *c*



$$\ln\left(\frac{N}{N_0}\right) = A \exp\left\{-\exp\left[\frac{\mu_{\max} \exp(1)}{A}(L - t) + 1\right]\right\} \quad (2)$$

where *N* is the population density at time *t* (the index 0 denotes initial values).

Gibson et al. [15] also proposed a modification for the Gompertz equation, as follows:

$$\log N = A + C \exp\{-\exp[-B(t - M)]\} \quad (3)$$

and considered:

$$\text{Growth rate} = \frac{BC}{e} \quad (4)$$

$$\text{lag} = M - \frac{1}{B} \quad (5)$$

$$\text{Generation time} = \frac{24 \times \log(2) \times \exp(1)}{B \times C} \quad (6)$$

where the generation time is the time at which the absolute growth rate is maximum.

Expressions 2 and 3 are identical, if Eq. 3 is normalized in relation to *N*₀. Zwietering et al. [49] expressed $\ln(N/N_0)$ as a function of time, while Gibson et al. [15] used $\log(N)$.

Some authors found that the growth rate of the modified Gompertz equation is most of the times significantly larger than the growth rate identified by an exponential model or by the Baranyi model [2]. In Baty and Delignette-Muller [4], it is stated that: “The limitations in the use of the modified Gompertz model have been widely discussed, attention being particularly paid to the overestimation of μ_{\max} and lag time”. However, these affirmations are based on the works of Whiting and Cygnarowicz-Provost [46], Dalgaard [11], Membre et al. [30] and McKellar and Knight [27] and, besides the remarkable approach of Baty and Delignette-Muller [4] about estimation of lag time, these authors were not critical about the works they had based their conclusions. In such works, model parameters were estimated, but uncertainty was not quantified (e.g. confidence intervals). The unknown parameter should not be evaluated by the estimated value itself, but should be assessed by the interval within the true value of the parameter is expected to lie, based on a pre-establish

significance level (i.e. confidence intervals that allows comparison of precision of different parameters). Consequently, saying that an overestimation occurs (Dalgaard [11] referred that an overestimation of 10–20% was observed for μ_{\max}) is limited to the value of the estimates. Obviously, this is a confined conclusion, and there is no statistical evidence that an overestimation had been attained.

Modifications of the Gompertz Model to Describe Inactivation

Different approaches had been proposed to modify the original Gompertz model to describe inactivation. Nevertheless, a critical review of the drawbacks/advantages of those modified and re-parameterized functions is lacking.

If experimental data is normalized in order to *N*₀, it is possible to compare kinetic behaviour of experimental data with different initial inoculum’s size. In the work of Miller et al. [31], the assumed dependent variable was the logarithm of the normalized values of the microbial load, $\log(N/N_0)$. The symmetric about the *x*-axis of the original Gompertz equation for growth (i.e. replacing *y* by $-y$ in its original form) was assumed for inactivation (Table 1, Approach 1).

Linton et al. [24] also considered $\log(N/N_0)$ as the dependent variable, and the mathematical function for inactivation was obtained by subtracting the original Gompertz expression at time zero from the one at time *t* (Table 1, Approach 2).

Gil et al. [17] assumed that the dependent variable was the logarithm of the microbial load, $\log N$, and the original Gompertz equation was subtracted from a constant (Table 1, Approach 3).

According to Garthright [13], the reason for applying logarithmic of different bases (i.e. *ln* or *log*) to microbial content is not stated. The only difference is related to the vertical axis scale. However, and as microbiological dilutions are powers of 10, “log” is a more convenient form.

Table 1 Modifications of the Gompertz model and re-parameterized forms that describe inactivation behaviour

Function for inactivation	Function limits	Derivative with respect to time	Interception of the extrapolated tangent line through the inflexion point (with time axis, or initial value in approach 3)	Re-parameterized form
<p>Approach 1</p> $y_{\text{inact}}(t) = \log\left(\frac{N}{N_0}\right) = -y_{\text{orig}}(t)$ <p>Miller et al. [31]</p>	$y_{\text{inact}}(t \rightarrow \infty) = -a$ $y_{\text{inact}}(t \rightarrow 0) = \log\left(\frac{N_{\text{res}}}{N_0}\right) \times \exp(-\exp(b))$	$\frac{dy_{\text{inact}}}{dt} = -ac \exp(-\exp(b - ct)) \times (\exp(b - ct))$	$k_{\text{max}}L - \frac{a}{c} - k_{\text{max}}\left(\frac{b}{c}\right) = 0$	$y_{\text{inact}}(t) = \log\left(\frac{N_{\text{res}}}{N_0}\right) \exp\left(-\exp\left(\frac{k_{\text{max}}e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)}(L - t) + 1\right)\right)$ $a = -\log\left(\frac{N_{\text{res}}}{N_0}\right)$ $c = \frac{k_{\text{max}}\exp(1)}{a}$ $b = Lc + 1$
<p>Approach 2</p> $y_{\text{inact}}(t) = \log\left(\frac{N}{N_0}\right) = y_{\text{orig}}(t) - y_{\text{orig}}(t = 0)$ <p>Linton et al. [24]</p>	$y_{\text{inact}}(t \rightarrow \infty) = a$ $y_{\text{inact}}(t \rightarrow 0) = 0$	$\frac{dy_{\text{inact}}}{dt} = ac \exp(-\exp(b - ct)) \times (\exp(b - ct))$	$\frac{a}{c} - a \exp(-\exp(b)) - \frac{b}{c}k_{\text{max}} + k_{\text{max}}L = 0$	$y_{\text{inact}}(t) = \log\left(\frac{N_{\text{res}}}{N_0}\right) \exp\left(-\exp\left(\frac{k_{\text{max}}e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)}(L - t) + 1\right)\right) - \log\left(\frac{N_{\text{res}}}{N_0}\right) \exp\left(-\exp\left(L - \frac{k_{\text{max}}e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)} + 1\right)\right)$ $a = \log\left(\frac{N_{\text{res}}}{N_0}\right)$ $c = \frac{k_{\text{max}}\exp(1)}{a}$ $b = Lc + 1$
<p>Approach 3</p> $y_{\text{inact}}(t) = \log(N) = \text{const} - y_{\text{orig}}(t)$ <p>Gibson et al. [15]</p>	$y_{\text{inact}}(t \rightarrow \infty) = D - a$ $y_{\text{inact}}(t \rightarrow 0) = D - a \times \exp(-\exp(b))$	$\frac{dy_{\text{inact}}}{dt} = ac \exp(-\exp(b - ct)) \times (\exp(b - ct))$	$D - \frac{a}{c} - k_{\text{max}}\frac{b}{c} + k_{\text{max}}L = 0$	$y_{\text{inact}}(t) = \log(N_0) + \log\left(\frac{N_{\text{res}}}{N_0}\right) \times \exp\left(-\exp\left(\frac{k_{\text{max}}e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)}(L - t) + 1\right)\right)$ $a = -\log\left(\frac{N_{\text{res}}}{N_0}\right)$ $c = \frac{k_{\text{max}}\exp(1)}{a}$ $b = Lc + 1$

Analytical Study of the Functions

Based on functions' analytical study (e.g. function limits and derivatives), inactivation functions can be re-parameterized in more convenient expressions.

The tail effect, which is a residual population, can be estimated by the asymptote of the function. Maximum inactivation rate can be obtained by calculating the first derivative at the curve inflexion point, t_i . The shoulder can be determined by the interception of the extrapolated tangent line with time axis (Table 1, approaches 1 and 2) or with initial value (Table 1, approach 3).

To clarify this methodology in the re-parameterization of the Gompertz model for inactivation, an example will be shown considering the approach 1. The dependent variable assumed is:

$$y_{\text{inact}}(t) = \log\left(\frac{N}{N_0}\right) = -y_{\text{orig}}(t) \tag{7}$$

Function Limits

The residual population (N_{res} , i.e. microbial load when time is considerably high) and initial microbial content (N_0 , i.e. microbial load when time is zero) can be calculated by function limits.

If $t \rightarrow \infty \Rightarrow y_{\text{inact}} \rightarrow -a$ Thus, parameter a can be substituted by $\log\left(\frac{N_0}{N_{\text{res}}}\right)$ or $(-a)$ substituted by $\log\left(\frac{N_{\text{res}}}{N_0}\right)$, corresponding to the tailing effect (asymptotic value).

Regarding the initial value:

$$t \rightarrow 0; \quad y_{\text{inact}} \rightarrow \log\left(\frac{N_{\text{res}}}{N_0}\right) \exp(-\exp(b)) \tag{8}$$

At $t = 0$, $\log N(t = 0) = \log N_0$, so $y_{\text{inact}}(0) = 0$. However, this is only observed if parameter b is high.

If b has a low value, then $y_{\text{inact}}(0)$ is not zero, being $y_{\text{inact}}(0) = \frac{\log\left(\frac{N_{\text{res}}}{N_0}\right)}{e}$. Nevertheless, this value is very small compared to $\log(N_{\text{res}}/N_0)$. The significance of this problem will be discussed later.

Function Derivatives

The maximum inactivation rate, k_{max} , can be obtained by calculating the function first derivative at the inflection point, t_i (determined by the zero of the second-order derivative):

$$\frac{dy_{\text{inact}}}{dt} = -ac \exp(-\exp(b - ct))(\exp(b - ct)) \tag{9}$$

Substituting t by $t_i = \frac{b}{c}$, one can obtain:

$$k_{\text{max}} = \left. \frac{dy_{\text{inact}}}{dt} \right|_{t=t_i} = -\frac{ac}{e} \tag{10}$$

thus, parameter c can be re-written as:

$$c = \frac{k_{\text{max}} e}{a} = \frac{k_{\text{max}} e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)} \tag{11}$$

The shoulder, L , is defined as the interception of the extrapolated tangent line through the inflexion point with time axis (or initial value in approach 3):

$$k_{\text{max}}L - \frac{a}{e} - k_{\text{max}}\left(\frac{b}{c}\right) = 0 \tag{12}$$

If Eqs. 11 and 12 are merged, parameter b can be expressed as:

$$b = 1 - \frac{Lk_{\text{max}}e}{a} \tag{13}$$

A re-parameterized expression for $y_{\text{inact}}(t)$ can be obtained by substitution of parameters a , b and c into Eq. 7:

$$y_{\text{inact}}(t) = \log\left(\frac{N_{\text{res}}}{N_0}\right) \exp\left(-\exp\left(\frac{k_{\text{max}} e}{\log\left(\frac{N_{\text{res}}}{N_0}\right)}(L - t) + 1\right)\right) \tag{14}$$

with the following parameters: shoulder (L), maximum inactivation rate (k_{max}) and tail $[\log(N_{\text{res}}/N_0)]$.

An outline of the analytical study of Gompertz-based functions, modified for inactivation, is in Table 1.

Drawbacks/Advantages of Re-parameterized Gompertz Functions

Concerning approach 1 and as discussed before, the function at time zero $[\log(N/N_0)(t = 0)]$ only approaches zero.

However, if the b parameter is higher than 1.6 (i.e. the ratio between $(k_{\text{max}} L)$ and $\log(N_{\text{res}}/N_0)$ is higher than 0.22), which is verified for microbial inactivation as mentioned by Van Impe et al. [43] and Garthright [13], then the overestimation in $\log(N/N_0)$ will be approximately 5%. This value is lower than the variations occurring between duplicates of microbial enumerations, which commonly vary between 10 and 60%.

The drawback in estimation microbial loads at time zero also appears in approach 2. Re-parameterization is only possible if the parameter b is high; otherwise, there is some inconsistency from a mathematical point of view.

Additionally, and in both approaches 1 and 2, $y_{\text{inact}}(t \rightarrow \infty)$ only approximates to $\log(N_{\text{res}}/N_0)$. This can be overcome by b value restrictions, as previously discussed. Nevertheless, both problems are limitations from a mathematical point of view and not from a biological aspect. In order to circumvent those weaknesses, an additional parameter was included in approach 3 (parameter D).

Gibson et al. [15] used this modified equation to avoid fitting problems at initial time. The mathematical study of the re-parameterized modification shows that $y_{\text{inact}}(0)$ is only equal to $\log(N_0)$ when $b \rightarrow \infty$, if not D can be a very poor estimator of $\log(N_0)$.

Non-isothermal Conditions

Non-isothermal conditions are more complex situations, as the temperature histories affect parameter estimation. The kinetic parameters estimated under time-varying temperature conditions may differ from the ones predicted at constant temperatures. Using the later ones, in situations in which the temperature varies with the time, may affect the predictive ability of the model [17].

Nicolaï and Van Impe [33] and Geeraerd et al. [14] were innovative in the way they approached the modelling of microbial growth and/or inactivation under dynamic temperature conditions. The works of Van Impe et al. [43] and Huang [19] were the first to refer Gompertz model modifications for non-isothermal conditions, including the temperature variations throughout the process.

According to Gil et al. [17], the mathematical expression for non-isothermal conditions can be obtained by differentiating the isothermal re-parameterized model with respect to time:

$$y_{\text{dynamic}}(t) = \int_0^t \frac{dy_{\text{inact}}(t)}{dt} dt \quad (15)$$

The model parameters, shoulder and maximum inactivation rate, are temperature dependent. In processes in which temperature varies with time, those parameters are obviously time–temperature relying. If the dependence of kinetic parameters on temperature is expressed mathematically and if the temperature history is known, those relationships may be included in Eq. 15. A mathematical model that describes the microbial content throughout time and temperature can thus be obtained.

Three main assumptions should be in the backstage of the model development, as highlighted in Valdramidis

et al. [40]: (1) no microbial growth occurs during the come-up time of the non-isothermal heat treatment; (2) there is a limit of temperature below which no inactivation is observed (i.e. inactivation rate is set to zero for temperatures lower than this limit) and (3) the temperature history has not a significant effect on the microbial heat resistance.

Huang [19] compared three mathematical models (linear, Weibull- and Gompertz-type models) to describe the inactivation of *L. Monocytogenes* in ground beef under both isothermal and non-isothermal conditions and concluded that the Gompertz was the only one capable of quantifying the behaviour in non-isothermal conditions.

A Case Study

A case study is presented to assess the three approaches outline. *Listeria innocua* thermal inactivation data in broth under isothermal conditions were considered at temperatures of 52.5, 55.0, 57.5, 60.0, 62.5 and 65.0 °C (data from [31]). The three functions that can be used for inactivation (Table 1) were fitted to experimental data by nonlinear regression analysis. All regression analysis procedures and calculations were performed in programs specially written in FORTRAN 77 language (Fortran 5.1, Microsoft Corporation®, 1990).

Results of data fits to experimental points are in Fig. 2; estimates of the parameters and results of regression analyses are shown in Table 2. Comparing the three re-parameterizations, one can conclude that all approaches are quite similar. Besides this similarity, it can be found that re-parameterized equations obtained in approaches 2 and 3 have problems, mainly when fitting experimental data without shoulder region or residual population (tail effect). In approach 3, this can be explained by the additional parameter $\log(N_0)$, which increases the collinearity.

It can be observed that all modified Gompertz models allowed accurate predictions of *Listeria innocua* inactivation in the temperature range considered (R_{adj}^2 between 0.944 and 0.992, which means that more than 94% of the total variation was explained by the model). The analysis

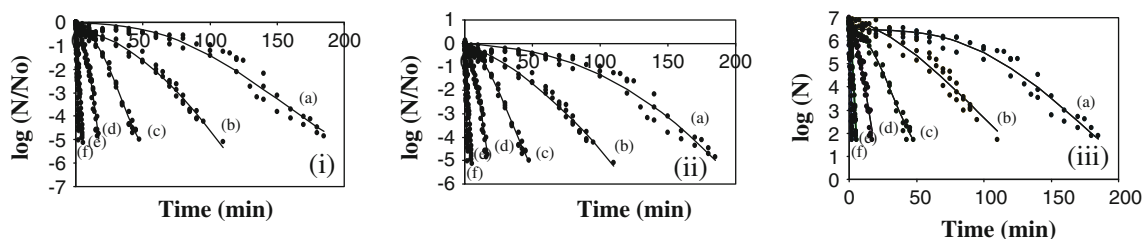


Fig. 2 Experimental data of thermal inactivation of *Listeria innocua* in broth (filled circle) and model fits (continuous line) at a 52.5 °C, b 55.0 °C, c 57.5 °C, d 60.0 °C, e 62.5 °C, f 65.0 °C: (i) approach 1, (ii) approach 2 and (iii) approach 3

Table 2 Parameters estimation and evaluation of precision; relevant statistical data of regression analysis

Function	T (°C)	Log(N ₀)	Parameter estimates			Standard half width error				Regression analysis	
			Log(N _{res} /N ₀)	k _{max} (min ⁻¹)	L (min)	SHW _{95%} log(N ₀)	SHW _{95%} log(N _{res} /N ₀) (%)	SHW _{95%} k _{max} (%)	SHW _{95%} L (%)	R ² _{adj}	Residuals normality
Approach 1	52.5	–	–9.3	–0.04	69.1	–	47.79	14.72	18.89	0.962	Yes
	55.0	–	–18.2	–0.08	39.6	–	55.36	29.63	46.60	0.984	Yes
	57.5	–	–8.3	–0.14	10.8	–	17.73	4.62	12.26	0.992	Yes
	60.0	–	–14.8	–0.45	6.1	–	69.21	31.95	49.80	0.970	Yes
	62.5	–	–7.6	–1.14	0.7	–	20.71	5.33	24.13	0.977	Yes
	65.0	–	–6.8	–2.18	0.0	–	23.50	7.98	321.70	0.971	Yes
Approach 2	52.5	–	–36.2	–0.08	129.0	–	227.00	136.20	108.90	0.966	Yes
	55.0	–	–35.0	–0.08	40.0	–	351.30	168.50	394.60	0.975	Yes
	57.5	–	–9.5	–0.14	9.3	–	32.26	5.80	18.51	0.991	Yes
	60.0	–	–14.3	–0.40	4.0	–	122.70	38.00	80.90	0.969	Yes
	62.5	–	–10.1	–1.10	0.0	–	59.66	6.65	∞	0.975	Yes
	65.0	–	–6.1	–2.53	0.0	–	33.71	17.25	∞	0.956	Yes
Approach 3	52.5	6.5	–11.8	–0.05	91.4	2.35	79.74	27.90	22.35	0.965	Yes
	55.0	7.6	–14.1	–0.06	15.0	20.72	193.6	48.23	165.00	0.947	Yes
	57.5	6.6	–7.4	–0.14	11.2	2.88	28.55	6.62	20.58	0.987	Yes
	60.0	7.6	–15.6	–0.37	2.0	31.26	260.3	63.74	241.70	0.944	Yes
	62.5	7.2	–10.4	–1.14	0.5	11.86	75.19	8.81	151.50	0.974	Yes
	65.0	6.6	–6.9	–2.21	0.0	18.83	63.58	15.78	∞	0.967	Yes

of the residuals showed that randomness was verified, as well as normality behaviour. A runs test [44] was carried out for detecting departures in randomness, and results proved that residuals were random in all cases. Overall, in terms of parameters' precision evaluated by the standardized half width of the estimates at 95% (SHW_{95%}, i.e. halved confidence interval divided by the estimate $\equiv \frac{\text{confidence interval } 95\%}{2} \times \frac{1}{\text{estimate}} \times 100$), better results were obtained when approach 1 was considered (i.e. lower SHW_{95%} values were obtained). For shoulder, k_{max} and tail, SHW_{95%} varied between 12–322%, 5–32% and 18–69%, respectively. When higher temperatures were considered, lowest precision was obtained for shoulder parameter. This can be an indication of lack of fit that may be explained by the decrease in the initial shoulder time. In such situation, better results might be obtained if another experimental design was chosen.

Based on these results and on inference bands of 95%, which are the prediction intervals for a future observed response [3], approach 1 was the elected one (Fig. 3). Nevertheless, the values of the estimated response for time zero only approaches zero. This limitation can be neglected when compared to the large experimental measuring error observed between initial inoculum's size duplicates (the difference between duplicates was within the range of 5.5–58%, depending on the temperature). This can also be accepted if inference bands are taken into consideration.

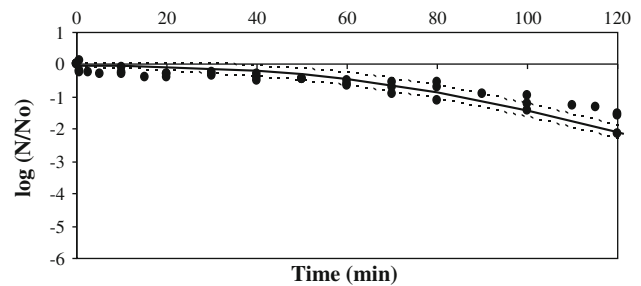


Fig. 3 Results from fitting the modified Gompertz model considering approach 1 (solid line) to the *Listeria innocua* inactivation data at 52.5 °C (filled circle). The dashed lines indicate the 95% inference bands of the response

Note, however, that parameter estimates should be used with caution for temperatures outside the experimental isothermal region (i.e. <52.5 and >65.0 °C) where extrapolation is made.

Concluding Remarks

Among nonlinear models, the Gompertz equation and its modified forms have been successfully applied to describe inactivation, both in terms of statistical accuracy and easiness of use, when compared to other sigmoidal functions.

The Gompertz equation does not assume a constant death rate. Rather, it is a model that can be used to model

death rates that change over time. However, there is a maximum value for the inactivation rate and k_{\max} expresses this feature (maximum slope of the curve). In re-parameterized forms, k_{\max} could be a model parameter, as well as the initial shoulder period and the tail residual population (when it occurs).

Besides the Gompertz model has some limitations from a mathematical point of view, it is effective for predictive purposes in microbial thermal inactivation responses, if convenient re-parameterized forms are applied.

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